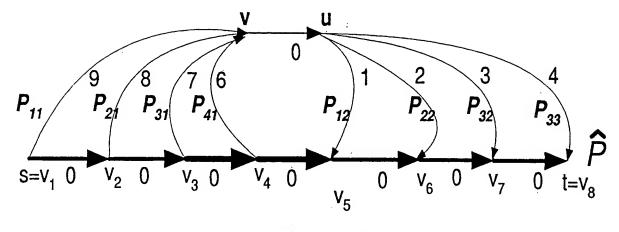


FIGURE 3.

```
Algorithm PP ( G(V, E), \hat{P}, \hat{d}, U)
   parameters:
      G(V, E) - network,
       \{d_l, c_l\}_{l \in E} - delays and costs of the network links,
      \hat{P} = \{s = v_0, v_1, ..., t = v_n\} - QoS path,
      \hat{d}- delay constraint,
      U- the upper bound on the cost of R.
  1 \Delta \leftarrow \hat{d} - D(\hat{P})
   2 \quad E' \leftarrow E
  3 for each link l = (v_i, v_{i+1}) \in \hat{\mathcal{P}} do
           E' \leftarrow E' \setminus \{(v_i, v_{i+1}) \in \hat{\mathcal{P}}\}\
           E' \leftarrow E' \cup \{(v_{i+1},v_i) \in \hat{\mathcal{P}}\}, \, c_{(v_{i+1},v_i)} \leftarrow 0
       for all v_i \in V do
           D_{v_i}[0] \leftarrow \infty
       D_s[0] \leftarrow 0
      for c = 1, 2, ..., U do
          for each v_j \in V in order such that v_j is before v_{j'} if v_j is a successor of v_{j'} in \hat{\mathcal{P}} do
 11
              D_{v_i}[c] \leftarrow D_{v_i}[c-1]
              for each link l=(v_i,v_j)\in E' do
12
 13
                 RELAX(l(v_i, v_j), c, \Delta)
14
           if D_t[c] \leq D(\hat{\mathcal{P}}) then
15
              determine walk W by backtracking
16
              return W.
17 return FAIL
       Procedure RELAX (l = (v_i, v_j), c, \Delta)
  1 if v_j \in \hat{\mathcal{P}} and v_i \in \hat{\mathcal{P}} then
          if D_{v_i}[c] \leq D(\hat{\mathcal{P}}_{(s,v_i)}) then
              D_{v_j}[c] \leftarrow \min\{D_{v_j}[c], D(\hat{\mathcal{P}}_{(s,v_j)})\}
  3
  4
       else
  5
          if c_l \leq c then
  6
              D_{v_j}[c] \leftarrow \min\{D_{v_j}[c], D_{v_i}[c-c_l] + d_l\}
          if v_j \in \hat{\mathcal{P}} and D_{v_j}[c] \leq D(\hat{\mathcal{P}}_{(s,v_j)}) + \Delta then
  7
              D_{v_j}[c] \leftarrow \min\{D_{v_j}[c], D(\hat{\mathcal{P}}_{(s,v_j)})\}
```

```
Algorithm RT ( G(V,E),\hat{\mathcal{P}},\hat{d},arepsilon)
  parameters:
      G(V, E) - network
      \hat{P} = \{s = v_1, v_2, ..., t = v_n\} - QoS path,
      \hat{d}- delay constraint
      \varepsilon- approximation ratio
   1 L, U \leftarrow BOUND(G(V, E), \hat{P}, \hat{d})
           B \leftarrow \sqrt{L \cdot U}
   3
           if \mathrm{TEST}(G(V,E),\hat{\mathcal{P}},\hat{d},B,\varepsilon) returns YES then
           else
              U \leftarrow 2 \cdot B
   8 until U/L \le 8.
   9 \mathcal{W} \leftarrow \text{SCALE}(G(V, E), \hat{\mathcal{P}}, \hat{d}, L, U, \varepsilon)
  10 return the restoration topology that corresponds to W.
       Procedure SCALE(G(V, E), \hat{P}, \hat{d}, L, U, \varepsilon)
    1 S \leftarrow \frac{L\epsilon}{2N}
    2 for each link l \in E do
           c_i' \leftarrow \lfloor \frac{c_i'}{s} \rfloor + 1
    4 \tilde{U} \leftarrow \left| \frac{U}{S} \right| + 2N
    5 return PP(G(V, E), \{d_l, c'_l\}_{l \in E}, \hat{\mathcal{P}}, \hat{d}, \tilde{U})
        Procedure TEST(G(V, E), \hat{P}, \hat{d}, B)
    1 Apply Procedure SCALE for (G(V, E), \hat{P}, \hat{d}, B, B, 2)
    2 if Algorithm SCALE returned FAIL then
            return NO
         else
    4
              return YES
        Procedure BOUND(G(V, E), \hat{P}, \hat{d})
    1 let c^1 < c^2 < \cdots < c^r the distinct costs values of the
         links.
    2 low \leftarrow 1; high \leftarrow r
    3 while low < high - 1
            j \leftarrow \lfloor (high + low)/2 \rfloor
           E' \leftarrow \{l \mid c_l \leq c^j\}
             set c_l \leftarrow 1 for each l \in E'
             apply Algorithm PP on (G'(V, E'), \hat{P}, \hat{d}, 2N)
             if Algorithm PP returned FAIL then
                high \leftarrow j
    10
                low \leftarrow j
    11
    12 U \leftarrow 2N \cdot c^{high}; L \leftarrow c^{high};
    13 return L, U;
```



后一次已经

FIGURES

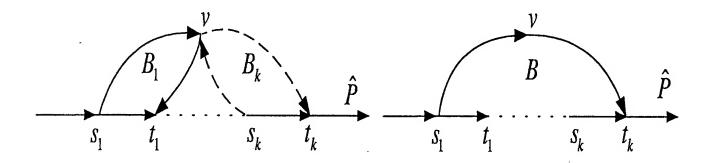


FIGURE 7

```
Algorithm DRT ( G(V,E),\hat{\mathcal{P}},\hat{d},arepsilon)
  parameters: G(V, E) - network
     \hat{\mathcal{P}} = \{s = v_1, v_2, ..., t = v_n\} - QoS path,
     \hat{d}- delay constraint
     \varepsilon- approximation ratio
  1 \hat{d}' \leftarrow 2\hat{d} - D(\hat{P})
     L, U \leftarrow \mathtt{BOUND}(G(V, E), \hat{\mathcal{P}}, \hat{d}')
  3 do
          B \leftarrow \sqrt{L \cdot U}
          Apply Procedure SCALE for G(V, E), \hat{\mathcal{P}}, \hat{d}', B, B, \varepsilon
          if Procedure SCALE return FAIL then
             L \leftarrow B
          else
             Set {\mathcal W} be the walk returned by Procedure SCALE
  9
             if C(W) \leq L then
10
                return the restoration topology \mathcal R that corresponds to \mathcal W.
11
12
             else
13
                U \leftarrow 2 \cdot B,
14
       until U/L \leq 8.
       Apply Procedure SCALE for (G(V,E),\hat{\mathcal{P}},\hat{d}',L,U,arepsilon)
       if Procedure SCALE does not fail then
          Set \mathcal{W} be the walk returned by Procedure SCALE
     return the restoration topology \mathcal{R} that corresponds to \mathcal{W}.
```

